# A Unified Approach to Computing the Zeros of Orthogonal Polynomials 

Ridha Moussa ${ }^{1}{ }^{(1)}$, James Tipton ${ }^{2}$ (ㅁ)

## Article Info

Received: 26 Aug 2023
Accepted: 21 Nov 2023
Published: 31 Dec 2023 doi:10.53570/jnt. 1350502

Research Article


#### Abstract

We present a unified approach to calculating the zeros of the classical orthogonal polynomials and discuss the electrostatic interpretation and its connection to the energy minimization problem. This approach works for the generalized Bessel polynomials, including the normalized reversed variant, as well as the Vieté-Pell and Vieté-Pell-Lucas polynomials. We briefly discuss the electrostatic interpretation for each aforesaid case and some recent advances. We provide zeros and error estimates for various cases of the Jacobi, Hermite, and Laguerre polynomials and offer a brief discussion of how the method was implemented symbolically and numerically with Maple. In conclusion, we provide possible avenues for future research.


Keywords Orthogonal polynomials, zeros, electrostatic interpretation
Mathematics Subject Classification (2020) 33C45, 42C05

## 1. Introduction

The Jacobi, Hermite, and Laguerre polynomials are called classical orthogonal polynomials. They have served as objects of study as early as the 19th century and found applications in physics and approximation and number theory. For example, the Jacobi polynomials contain the Legendre polynomials as a special case, the coefficients in the expansion of the gravitational potential associated to a point mass [1]. The last two chapters of Szegö's classic text [2] focus on applications to interpolation and mechanical quadrature. More recently, the theory of orthogonal polynomials was used to present a formulation of quantum mechanics [3]. The classical orthogonal polynomials may be characterized as solutions to a Sturm-Liouville type equation of the form:

$$
Q(x) y^{\prime \prime}+L(x) y^{\prime}+\lambda y=0
$$

In the case of the Jacobi polynomials, $Q(x)=1-x^{2}, L(x)=\beta-\alpha-(\alpha+\beta+2) x$, and $\lambda=n(n+\alpha+\beta+1)$. For the Hermite polynomials, $Q(x)=1, L(x)=-2 x$, and $\lambda=2 n$. For the generalized Laguerre polynomials, $Q(x)=x, L(x)=(\alpha+1-x)$, and $\lambda=n$. In each case, the corresponding polynomial solutions satisfy an orthogonality condition of the form

$$
\int_{-\infty}^{\infty} P_{m}(x) P_{n}(x) W(x) d x=0, \quad m \neq n
$$

[^0]where for the Jacobi polynomials,
\[

W(x)= $$
\begin{cases}(1-x)^{\alpha}(1+x)^{\beta}, & -1 \leq x \leq 1 \\ 0, & |x|>1\end{cases}
$$
\]

for the Hermite polynomials,

$$
W(x)=e^{-x^{2}}
$$

and for the generalized Laguerre polynomials,

$$
W(x)= \begin{cases}x^{\alpha} e^{-x}, & x \geq 0 \\ 0, & x<0\end{cases}
$$

Some topics of recent interest in the area of orthogonal polynomials include generalized Bessel polynomials [4], Vieté-Pell-Lucas polynomials [5, 6], and quasi-orthogonal polynomials [7]. Dunster et al. [4] study the reverse generalized Bessel polynomials by combining a qualitative analysis involving Liouville-Green Stokes lines and anti-Stokes lines with a fixed point method to calculate their zeros. Tasci and Yalcin [6] present some fundamental properties of Vieté-Pell and Vieté-Pell-Lucas polynomials, such as their characteristic equations, Binet formulas, and generating functions. More recently, Kuloğlu et al. [5] study a generalization of these polynomials, incomplete generalized Vieté-Pell and Vieté-Pell-Lucas polynomials, presenting recurrence relations and their generating functions. The well-known electrostatic interpretation is a central reason for continued interest in the zeros of classical and nonclassical orthogonal polynomials. Ismail $[8,9]$ extensively researches this topic, including a recent study on the general theory of quasi-orthogonal polynomials, which included an investigation into an electrostatic equilibrium problem [7]. Another point of interest is that these zeros have been used in quadrature rules [10-12].

The above treatment can be provided to both the (normalized reversed) generalized Bessel polynomials and the Vieté-Pell and Vieté-Pell-Lucas polynomials. Take $Q(x)=x^{2}, L(x)=\alpha x+\beta$, and $\lambda=$ $-n(n+\alpha-1)$, for the generalized Bessel polynomials, while the normalized reverse Bessel polynomials satisfy $Q(x)=x, L(x)=-(2 n-2+a+2 x)$, and $\lambda=2 n$ (for more details, see $[4,13]$ ). To provide Vieté-Pell and Vieté-Pell-Lucas polynomials a similar treatment, one can exploit their relationship to the Chebyshev polynomials to find that $Q(x)=4-x^{2}, L(x)=-3 x$, and $\lambda=n(n+1)$ for the Vieté-Pell polynomials and $Q(x)=4-x^{2}, L(x)=-x$, and $\lambda=n^{2}$ for the Vieté-Pell-Lucas polynomials.

We present a unified method to calculate the zeros of a class of orthogonal polynomials, including the classical orthogonal polynomials and generalized Bessel polynomials. We discuss the electrostatic interpretation for several cases and the connection to the energy minimization problem. The method in question differs from that used by Dunster et al. [4] and is more akin to an approach developed by Pasquini [14-16] and more recently [17]. In Section 2, we present the details of the method. In Section 3 , we discuss the electrostatic interpretation in the context of the energy minimization problem. We briefly outline how to implement the method symbolically and numerically in Section 4. In Section 5, we provide some examples. The paper concludes with possible avenues for future investigation.

## 2. Method

Given a polynomial $y=c_{n} \prod_{i=1}^{n}\left(x-x_{i}\right)$, where $c_{n}, x_{i} \in \mathbb{R}, c_{n} \neq 0$, and the $x_{i}$ are distinct,

$$
\begin{equation*}
\frac{y^{\prime}}{y}=\sum_{i=1}^{n} \frac{1}{x-x_{i}} \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\frac{y^{\prime \prime}}{y}=\sum_{i=1}^{n} \sum_{j \in J_{i}} \frac{1}{\left(x-x_{i}\right)\left(x-x_{j}\right)}=2 \sum_{i<j} \frac{1}{\left(x-x_{i}\right)\left(x-x_{j}\right)} \tag{2}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{a x^{2}+b x+c}{\left(x-x_{i}\right)\left(x-x_{j}\right)}=a+\frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}+\frac{a x_{j}^{2}+b_{j}+c}{\left(x_{j}-x_{i}\right)\left(x-x_{j}\right)} \tag{3}
\end{equation*}
$$

where $J_{i}$ consists of all integers in $[1, n]$ except $i$. Identities 1 and 2 follow from the product rule. Identity 3 follows from partial fraction decomposition.

Lemma 2.1. From the above setting,

$$
(\mu x+\nu) \frac{y^{\prime}}{y}=\mu n+\sum_{i=1}^{n} \frac{\nu+\mu x_{i}}{x-x_{i}}
$$

and

$$
\left(a x^{2}+b x+c\right) \frac{y^{\prime \prime}}{y}=a\left(n^{2}-n\right)+2 \sum_{i \neq j} \frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}
$$

Proof.
The first identity follows directly from Identity 1 and some long division. For the second identity, combine Identities 2 and 3 and get the equality

$$
\left(a x^{2}+b x+c\right) \frac{y^{\prime \prime}}{y}=2 \sum_{i<j}\left[a+\frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}+\frac{a x_{j}^{2}+b x_{j}+c}{\left(x_{j}-x_{i}\right)\left(x-x_{j}\right)}\right]
$$

There are $\frac{n^{2}-n}{2}$ terms in the above summation. Thus, $2 \sum_{i<j} a=a\left(n^{2}-n\right)$. Observe that

$$
\begin{aligned}
\sum_{i<j}\left[\frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}+\frac{a x_{j}^{2}+b x_{j}+c}{\left(x_{j}-x_{i}\right)\left(x-x_{j}\right)}\right] & =\sum_{i<j} \frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}+\sum_{i<j} \frac{a x_{j}^{2}+b x_{j}+c}{\left(x_{j}-x_{i}\right)\left(x-x_{j}\right)} \\
& =\sum_{i<j} \frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}+\sum_{j<i} \frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)} \\
& =\sum_{i \neq j} \frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}
\end{aligned}
$$

where the second to last equality follows from index swapping on the second summation. Putting the above calculations together yields the desired result.

Proposition 2.2. Suppose $y$ is a degree $n$ polynomial solution to the differential equation

$$
\left(a x^{2}+b x+c\right) y^{\prime \prime}+(\mu x+\nu) y^{\prime}+\kappa y=0
$$

If the zeros of $y, x_{1}, \cdots, x_{n}$ are distinct, then for each integer $k \in[1, n]$,

$$
2 \sum_{j \in J_{k}} \frac{a x_{k}^{2}+b x_{k}+c}{x_{k}-x_{j}}+\nu+\mu x_{k}=0
$$

Proof.
Divide by $y$ and apply Lemma 1 ,

$$
\begin{aligned}
& a\left(n^{2}-n\right)+2 \sum_{i \neq j} \frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}+\mu n+\sum_{i=1}^{n} \frac{\nu+\mu x_{i}}{x-x_{i}}+\kappa=0 \Leftrightarrow 2 \sum_{i \neq j} \frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)}+\sum_{i=1}^{n} \frac{\nu+\mu x_{i}}{x-x_{i}}+M=0 \\
& \Leftrightarrow 2\left(x-x_{k}\right) \sum_{i \neq j} \frac{a x_{i}^{2}+b x_{i}+c}{\left(x_{i}-x_{j}\right)\left(x-x_{i}\right)} \\
&+\left(x-x_{k}\right) \sum_{i=1}^{n} \frac{\nu+\mu x_{i}}{x-x_{i}}+\left(x-x_{k}\right) M=0
\end{aligned}
$$

where $M=\kappa+a\left(n^{2}-n\right)+\mu n$ and $k$ is some integer in $[1, n]$. As $x$ approaches $x_{k}$, all terms will approach zero except those for $i=k$. Taking this limit gives the desired result.

### 2.1. Jacobi Polynomials

For $\alpha, \beta>-1$, the degree $n$ Jacobi polynomial $P_{n}^{(\alpha, \beta)}(x)$ solves the differential equation

$$
\left(1-x^{2}\right) y^{\prime \prime}+(\beta-\alpha-(\alpha+\beta+2) x) y^{\prime}+n(n+\alpha+\beta+1) y=0
$$

Denote the $n$ distinct zeros of $P_{n}^{(\alpha, \beta)}(x)$ by $x_{1}, \cdots, x_{n}$. Let $a=-1, b=0, c=1, \mu=-(\alpha+\beta+2)$, and $\nu=\beta-\alpha$. By Proposition 2.2, we see that the zeros must satisfy

$$
\begin{equation*}
2 \sum_{j \in J_{k}} \frac{-x_{k}^{2}+1}{x_{k}-x_{j}}+\beta-\alpha-(\alpha+\beta+2) x_{k}=0 \Leftrightarrow \frac{\frac{1}{2}(\alpha+1)}{x_{k}-1}+\frac{\frac{1}{2}(\beta+1)}{x_{k}+1}+\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}=0 \tag{4}
\end{equation*}
$$

The following theorem, which we have adapted from the Marsden and Hoffman classic [18], expresses the well-known fact that a continuous real-valued function over a compact set must attain an absolute maximum:

Theorem 2.3. [18] Suppose $A \subset \mathbb{R}^{n}$ and let $f: A \rightarrow \mathbb{R}$ be continuous. If $K \subset A$ is compact, then $f$ is bounded on $K$. Furthermore, there exists an $x_{0} \in K$ such that $f\left(x_{0}\right)=\sup f(A)$.

In what follows, consider the real-valued function

$$
f(\vec{x})=\prod_{k=1}^{n}\left[\left(1-x_{k}\right)^{(\alpha+1) / 2}\left(1+x_{k}\right)^{(\beta+1) / 2}\right] \prod_{i<j}\left(x_{j}-x_{i}\right)
$$

defined over the set $D_{n}=\left\{\vec{x} \in \mathbb{R}^{n}:-1<x_{1}<x_{2}<\cdots<x_{n}<1\right\}$. Note that $f$ is smooth over $D_{n}$ and continuous on $\overline{D_{n}}$. Note that $f$ vanishes on the boundary of $D_{n}$ but is positive over $D_{n}$. Since $f$ must attain an absolute maximum in $\overline{D_{n}}$, the previous observations show that this maximum occurs in $D_{n}$ and must be a critical point.

Lemma 2.4. A point $\vec{x} \in D_{n}$ is a critical point of $f$ if and only if Expression 4 holds for $k \in$ $\{1,2,3, \cdots, n\}$.

Proof.
Consider instead

$$
\ln (f)=\sum_{k=1}^{n}\left[\frac{\alpha+1}{2} \ln \left(1-x_{k}\right)+\frac{\beta+1}{2} \ln \left(1+x_{k}\right)\right]+\sum_{i<j} \ln \left(x_{j}-x_{i}\right)
$$

we have that

$$
\frac{\partial \ln (f)}{\partial x_{k}}=\frac{f_{x_{k}}}{f}=\frac{\frac{1}{2}(\alpha+1)}{x_{k}-1}+\frac{\frac{1}{2}(\beta+1)}{x_{k}+1}+\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}
$$

demonstrating the claim.
Lemma 2.5. The function $\ln (f)$ has only one critical point in $D_{n}$.

## Proof.

The claim holds if we can show that $\ln (f)$ is concave in $D_{n}$. This, in turn, will follow if we can show that the Hessian of $\ln (f)$ is diagonally dominant and negative definite. To that extent, observe that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{k}^{2}}=\frac{-\frac{1}{2}(\alpha+1)}{\left(x_{k}-1\right)^{2}}-\frac{\frac{1}{2}(\beta+1)}{\left(x_{k}+1\right)^{2}}-\sum_{j \in J_{k}} \frac{1}{\left(x_{k}-x_{j}\right)^{2}}
$$

and for $i \neq j$ that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{i} x_{j}}=\frac{1}{\left(x_{i}-x_{j}\right)^{2}}
$$

The Hessian is thus diagonally dominant and negative definite.
Example 2.6. To see the above results in action, set $\alpha=\beta=0$, giving the Legendre differential equation:

$$
\left(1-x^{2}\right) y^{\prime \prime}-2 x y^{\prime}+n(n+1) y=0
$$

The general solution is

$$
y=k_{1} P_{n}(x)+k_{2} Q_{n}(x)
$$

where

$$
P_{n}(x)=\frac{1}{2^{n} n!} \frac{d^{n}}{d x^{n}}\left(x^{2}-1\right)^{n}
$$

is the $n$-th Legendre polynomial and

$$
Q_{n}= \begin{cases}\frac{1}{2} \log \frac{1+x}{1-x}, & \text { if } n=0 \\ P_{1}(x) Q_{0}(x)-1, & \text { if } n=1 \\ \frac{2 n-1}{n} Q_{n-1}(x)-\frac{n-1}{n} Q_{n-2}(x), & \text { if } n \geq 2\end{cases}
$$

is the $n$-th Legendre function of the second kind [2]. For $n=2$, the second Legendre polynomial $P_{2}(x)=\frac{3 x^{2}-1}{2}$ solves the following differential equation:

$$
\left(1-x^{2}\right) y^{\prime \prime}-2 x y^{\prime}+6 y=0
$$

The corresponding real-valued function on $D_{2}$ is

$$
f\left(x_{1}, x_{2}\right)=\left(x_{2}-x_{1}\right) \sqrt{\left(1-x_{1}^{2}\right)\left(1-x_{2}^{2}\right)}
$$

which attains a global maximum at $x_{1}=-1 / \sqrt{3}$ and $x_{2}=1 / \sqrt{3}$. It is clear that $P_{2}\left(x_{1}\right)=P_{2}\left(x_{2}\right)=0$.

### 2.2. Hermite Polynomials

The degree $n$ Hermite polynomial $H_{n}(x)$ solves the differential equation $y^{\prime \prime}-2 x y^{\prime}+2 n y=0$. Denote the $n$ distinct zeros of $H_{n}(x)$ by $x_{1}, \cdots, x_{n}$. Let $a=b=\nu=0, c=1, \mu=-2$, and $\kappa=2 n$. By Proposition 2.2, we observe that the zeros must satisfy

$$
\begin{equation*}
2 \sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}-2 x_{k}=0 \Leftrightarrow \sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}-x_{k}=0 \tag{5}
\end{equation*}
$$

In what follows, consider the real-valued function

$$
f(\vec{x})=\prod_{i<j}\left[x_{j}-x_{i}\right] e^{-\frac{1}{2} \sum_{k=1}^{n} x_{k}^{2}}
$$

defined over the set $D_{n}=\left\{\vec{x} \in \mathbb{R}^{n}:-\infty<x_{1}<x_{2}<\cdots<x_{n}<\infty\right\}$. Note that $f$ is smooth, positive and bounded over $D_{n}$ but approaches 0 on the boundary. Thus, $f$ must have a critical point in $D_{n}$.

Lemma 2.7. A point $\vec{x} \in D_{n}$ is a critical point of $f$ if and only if Expression 5 holds for $k \in$ $\{1,2,3, \cdots, n\}$.

Proof.
Consider instead

$$
\ln (f)=\sum_{i<j} \ln \left(x_{j}-x_{i}\right)-\frac{1}{2} \sum_{k=1}^{n} x_{k}^{2}
$$

we have that

$$
\frac{\partial \ln (f)}{\partial x_{k}}=\frac{f_{x_{k}}}{f}=\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}-x_{k}
$$

demonstrating the claim.
Lemma 2.8. The function $\ln (f)$ has only one critical point in $D_{n}$.
Proof.
The claim holds if we can show that $\ln (f)$ is concave in $D_{n}$. This, in turn, will follow if we can show that the Hessian of $\ln (f)$ is diagonally dominant and negative definite. To that extent, observe that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{k}^{2}}=-\sum_{j \in J_{k}} \frac{1}{\left(x_{k}-x_{j}\right)^{2}}-1
$$

and for $i \neq j$ that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{i} x_{j}}=\frac{1}{\left(x_{i}-x_{j}\right)^{2}}
$$

The Hessian is thus diagonally dominant and negative definite.

### 2.3. Laguerre Polynomials

The degree $n$ generalized Laguerre polynomial $L_{n}^{(\alpha)}(x)$ solves the differential equation

$$
x y^{\prime \prime}+(\alpha+1-x) y^{\prime}+n y=0
$$

Denote the $n$ distinct zeros of $L_{n}^{(\alpha)}(x)$ by $x_{1}, \cdots, x_{n}$. Let $a=c=0, b=1, \mu=-1, \nu=\alpha+1$, and $\kappa=n$. By Proposition 2.2, we see that the zeros must satisfy

$$
\begin{equation*}
2 \sum_{j \in J_{k}} \frac{x_{k}}{x_{k}-x_{j}}+\alpha+1-x_{k}=0 \Leftrightarrow \sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}+\frac{\frac{1}{2}(\alpha+1)}{x_{k}}-\frac{1}{2}=0 \tag{6}
\end{equation*}
$$

In what follows, consider the real-valued function

$$
f(\vec{x})=\prod_{i<j}\left[x_{j}-x_{i}\right] \prod_{k=1}^{n}\left[x_{k}^{(\alpha+1) / 2}\right] e^{-\frac{1}{2} \sum_{k=1}^{n} x_{k}}
$$

defined over the set $D_{n}=\left\{\vec{x} \in \mathbb{R}^{n}: 0<x_{1}<x_{2}<\cdots<x_{n}<\infty\right\}$. Note that $f$ is smooth, positive and bounded over $D_{n}$ but approaches 0 on the boundary. Thus, $f$ must have a critical point in $D_{n}$.

Lemma 2.9. A point $\vec{x} \in D_{n}$ is a critical point of $f$ if and only if Expression 6 holds for $k \in$ $\{1,2,3, \cdots, n\}$.

Proof.
Consider instead

$$
\ln (f)=\sum_{i<j} \ln \left(x_{j}-x_{i}\right)+\sum_{k=1}^{n}\left[\frac{\alpha+1}{2} \ln x_{k}\right]-\frac{1}{2} \sum_{k=1}^{n} x_{k}
$$

we have that

$$
\frac{\partial \ln (f)}{\partial x_{k}}=\frac{f_{x_{k}}}{f}=\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}+\frac{\frac{1}{2}(\alpha+1)}{x_{k}}-\frac{1}{2}
$$

demonstrating the claim.
Lemma 2.10. The function $\ln (f)$ has only one critical point in $D_{n}$.
Proof.
The claim holds if we can show that $\ln (f)$ is concave in $D_{n}$. This, in turn, will follow if we can show that the Hessian of $\ln (f)$ is diagonally dominant and negative definite. To that extent, observe that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{k}^{2}}=-\sum_{j \in J_{k}} \frac{1}{\left(x_{k}-x_{j}\right)^{2}}-\frac{\frac{1}{2}(\alpha+1)}{x_{k}^{2}}<0
$$

and for $i \neq j$ that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{i} x_{j}}=\frac{1}{\left(x_{i}-x_{j}\right)^{2}}
$$

The Hessian is thus diagonally dominant and negative definite.

### 2.4. Normalized Reversed Generalized Bessel Polynomials

The normalized reversed generalized Bessel polynomials (RGBP)

$$
\hat{\theta}_{n}(z ; a)=\theta_{n}\left(\frac{(2 n+a-2) z}{2} ; a\right)
$$

satisfy the differential equation

$$
\frac{2 z}{2 n+a-2} \hat{\theta}_{n}^{\prime \prime}-(2 z+2) \hat{\theta}_{n}^{\prime}+2 n \hat{\theta}_{n}=0
$$

Applying Proposition 2.2,

$$
\begin{equation*}
\sum_{j \in J_{k}} \frac{1}{z_{k}-z_{j}}+\frac{M_{n, a}}{z_{k}}+M_{n, a}=0 \tag{7}
\end{equation*}
$$

where $M_{n, a}=\frac{2-2 n-a}{2}$, which correspond to the critical points of the function

$$
f(\vec{z})=\prod_{i<j}\left(z_{j}-z_{i}\right) \prod_{i=1}^{n}\left(z_{i}^{M_{n, a}}\right) e^{M_{n, a} \sum z_{i}}
$$

with domain $D_{n}=\left\{\vec{z}: z_{i} \neq z_{j}\right.$ if $\left.i \neq j\right\}$.
Lemma 2.11. A point $\vec{z} \in D_{n}$ is a critical point of $f$ if and only if Equation 7 holds for $k \in$ $\{1,2,3, \cdots, n\}$.

Proof.
Consider instead

$$
\ln (f)=\sum_{i<j} \ln \left(z_{j}-z_{i}\right)+M_{n, a} \sum_{i=1}^{n} \ln z_{i}-M_{n, a} \sum_{i=1}^{n} z_{k}
$$

we have that

$$
\frac{\partial \ln (f)}{\partial z_{k}}=\frac{f_{z_{k}}}{f}=\sum_{j \in J_{k}} \frac{1}{z_{k}-z_{j}}+\frac{M_{n, a}}{z_{k}}-M_{n, a}
$$

demonstrating the claim.
Lemma 2.12. The function $\ln (f)$ has only one critical point in $D_{n}$.

## Proof.

The claim holds if we can show that $\ln (f)$ is concave in $D_{n}$. This, in turn, will follow if we can show that the Hessian of $\ln (f)$ is diagonally dominant and negative definite. To that extent, observe that

$$
\frac{\partial^{2} \ln (f)}{\partial z_{k}^{2}}=-\sum_{j \in J_{k}} \frac{1}{\left(z_{k}-z_{j}\right)^{2}}-\frac{M_{n, a}}{z_{k}^{2}}
$$

and for $i \neq j$ that

$$
\frac{\partial^{2} \ln (f)}{\partial z_{i} z_{j}}=\frac{1}{\left(z_{i}-z_{j}\right)^{2}}
$$

The Hessian is thus diagonally dominant and negative definite.

### 2.5. Generalized Bessel Polynomials

In the case of generalized Beesel Polynomials (GBP), which satisfies the differential equation $x^{2} y^{\prime \prime}+$ $(\alpha x+\beta) y^{\prime}+n(n+\alpha-1) y=0$, we can take $a=1, b=c=0, \mu=\alpha, \nu=\beta$, and $\kappa=n(n+\alpha-1)$, to get that the zeros of the $n$th GBP satisfy

$$
\begin{equation*}
\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}+\frac{\frac{1}{2} \beta}{x_{k}^{2}}+\frac{\frac{1}{2} \alpha}{x_{k}}=0 \tag{8}
\end{equation*}
$$

These correspond to the critical points of the function

$$
f(\vec{x})=\prod_{i<j}\left(x_{j}-x_{i}\right) \prod_{i=1}^{n}\left(x_{i}^{\alpha / 2}\right) e^{-\frac{1}{2} \beta \sum 1 / x_{i}}
$$

with domain $D_{n}=\left\{\vec{x}: x_{i} \neq x_{j}\right.$ if $\left.i \neq j\right\}$.
Lemma 2.13. A point $\vec{x} \in D_{n}$ is a critical point of $f$ if and only if Equation 8 holds for $k \in$ $\{1,2,3, \cdots, n\}$.

Proof.
Consider instead

$$
\ln (f)=\sum_{i<j} \ln \left(x_{j}-x_{i}\right)+\frac{\alpha}{2} \sum_{i=1}^{n} \ln x_{i}-\frac{\beta}{2} \sum_{i=1}^{n} \frac{1}{x_{i}}
$$

we have that

$$
\frac{\partial \ln (f)}{\partial x_{k}}=\frac{f_{x_{k}}}{f}=\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}+\frac{\frac{1}{2} \alpha}{x_{k}}+\frac{\frac{1}{2} \beta}{x_{k}^{2}}
$$

demonstrating the claim.
Lemma 2.14. The function $\ln (f)$ has only one critical point in $D_{n}$.
Proof.
The claim holds if we can show that $\ln (f)$ is concave in $D_{n}$. This, in turn, will follow if we can show that the Hessian of $\ln (f)$ is diagonally dominant and negative definite. To that extent, observe that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{k}^{2}}=-\sum_{j \in J_{k}} \frac{1}{\left(x_{k}-x_{j}\right)^{2}}-\frac{\frac{1}{2} \alpha}{x_{k}^{2}}-\frac{\frac{1}{2} \beta}{x_{k}^{2}}
$$

and for $i \neq j$ that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{i} x_{j}}=-\sum_{j \in J_{k}} \frac{1}{\left(x_{i}-x_{j}\right)^{2}}
$$

The Hessian is thus diagonally dominant and negative definite.

### 2.6. Vieté-Pell and Vieté-Pell-Lucas Polynomials

Vieté-Pell polynomials satisfy the differential equation $\left(4-x^{2}\right) y^{\prime \prime}-3 x y^{\prime}+n(n+1) y=0$ and Vieté-Pell-Lucas polynomials satisfy the differential equation $\left(4-x^{2}\right) y^{\prime \prime}-x y^{\prime}+n^{2} y=0$ where $n$ is the degree of the polynomial. Applying Proposition 2.2 in each case, we find that the zeros satisfy

$$
\begin{equation*}
\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}+\frac{\frac{3}{4}}{x_{k}+2}+\frac{\frac{3}{4}}{x_{k}-2}=0 \tag{9}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}+\frac{\frac{1}{2}}{x_{k}+2}+\frac{\frac{1}{2}}{x_{k}-2}=0 \tag{10}
\end{equation*}
$$

respectively. Consider the functions

$$
f(\vec{x})=\prod_{k=1}^{n}\left[\left(2-x_{k}\right)^{\frac{3}{4}}\left(2+x_{k}\right)^{\frac{3}{4}}\right] \prod_{i<j}\left(x_{j}-x_{i}\right)
$$

and

$$
g(\vec{x})=\prod_{k=1}^{n}\left[\left(2-x_{k}\right)^{\frac{1}{2}}\left(2+x_{k}\right)^{\frac{1}{2}}\right] \prod_{i<j}\left(x_{j}-x_{i}\right)
$$

Proceeding as in the Jacobi case, one finds that:
Lemma 2.15. A point $\vec{x} \in D_{n}$ is a critical point of $f$ (resp. g) if and only if Equation 9 (resp. Equation 10) holds for $k \in\{1,2, \cdots, n\}$.

Proof.
Consider instead

$$
\ln (f)=\sum_{i<j} \ln \left(x_{j}-x_{i}\right)+\frac{3}{4} \sum_{i=1}^{n} \ln \left(2-x_{i}\right)+\frac{3}{4} \sum_{i=1}^{n} \ln \left(2+x_{i}\right)
$$

we have that

$$
\frac{\partial \ln (f)}{\partial x_{k}}=\frac{f_{x_{k}}}{f}=\sum_{j \in J_{k}} \frac{1}{x_{k}-x_{j}}+\frac{\frac{3}{4}}{x_{k}-2}+\frac{\frac{3}{4}}{x_{k}+2}
$$

demonstrating the claim for $f$. For $g$, replace $\frac{3}{4}$ with $\frac{1}{2}$.
Lemma 2.16. The functions $\ln (f)$ and $\ln (g)$ have only one critical point in $D_{n}$.
Proof.
The claim holds if we can show that both $\ln (f)$ and $\ln (g)$ are concave in $D_{n}$. This, in turn, will follow if we can show that their Hessians are diagonally dominant and negative definite. To that extent, observe that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{k}^{2}}=-\sum_{j \in J_{k}} \frac{1}{\left(x_{k}-x_{j}\right)^{2}}-\frac{\frac{3}{4}}{\left(x_{k}-2\right)^{2}}-\frac{\frac{3}{4}}{\left(x_{k}+2\right)^{2}}
$$

and for $i \neq j$ that

$$
\frac{\partial^{2} \ln (f)}{\partial x_{i} x_{j}}=-\sum_{j \in J_{k}} \frac{1}{\left(x_{i}-x_{j}\right)^{2}}
$$

For $g$, replace $\frac{3}{4}$ with $\frac{1}{2}$. In either case, the Hessian is thus diagonally dominant and negative definite.

## 3. Electrostatic Interpretation and the Connection to the Energy Minimization Problem

As detailed by Szego in [2], the zeros of the classical orthogonal polynomials may be interpreted as the equilibrium position of an electrostatic problem. Stieltjes derived this connection in the case of the Jacobi polynomials in 1885. In this case, the problem is to find the position of $n \geq 2$ unit masses in the interval $[-1,1]$ given two fixed positive masses $\frac{\alpha+1}{2}$ and $\frac{\beta+1}{2}$ at -1 and 1 , respectively, for which electrostatic equilibrium is attained. The problem is solved by locating the zeros of the Jacobi polynomial $P_{n}^{(\alpha, \beta)}(x)$ [2]. Stieltjes provided a similar interpretation to the other classical orthogonal polynomials. The unit "masses" lie in the interval $(0, \infty)$ for the Laguerre polynomials with the restriction that the arithmetic mean of the unit charges is uniformly bounded and $(-\infty, \infty)$ for the Hermite polynomials with the restriction that the square arithmetic mean of the unit charges is uniformly bounded $[2,19]$.

A similar electrostatic interpretation may be presented for Vieté-Pell and Vieté-Pell-Lucas polynomials; the unit masses lie in the interval $[-2,2]$, where we have positive mass $\frac{3}{4}$ at both -2 and 2 in Vieté-Pell case and positive mass $\frac{1}{2}$ at both -2 and 2 in Vieté-Pell-Lucas case. To the best of our knowledge, an electrostatic interpretation for the normalized RGBP and the GBP remains open. Interest in this connection has been steadily growing; see Marcellán, Martínez-Finkelshtein and Martínez-González's excellent survey [19] for details. As noted in [19], this is due in part to advances in the theory of logarithmic potentials as well as special functions from other areas of study, such as physics, combinatorics and number theory. Marcellán et al. [19] consider the following natural questions:
i. Can the electrostatic interpretation be generalized to other families of polynomials?
ii. Is it necessary to consider the global minimum of the energy? What about other equilibria?

In regards to the first question, it is noted in [19] that Ismail $[8,9]$ has provided an electrostatic model for general orthogonal polynomials, in which the external field is given as the sum of a long-range and short-range potential. For example, in [8], an explicit formula is given for the total energy of the model at the equilibrium position, and this energy is shown to be minimum. In the case of Freud weights, the total energy is shown to be asymptotic to $\frac{-n^{2}}{\alpha} \ln n$.
The authors [19] consider a more general case where the weight function satisfies the Pearson equation, particularly with the weight function corresponding to the Freud-type polynomials. It is noted that, in this case, the zeros of the Freud-type polynomials provide a critical configuration for the total energy. Still, it is an open problem whether the zeros are in a stable equilibrium. Regarding the second question, it is posited whether other types of equilibria are preserved in this case. The authors [19] present a max-min characterization of the zeros of the Jacobi polynomials, which is amenable to complex zeros of the family when the parameters fall out of the "classical" bounds. Loosely speaking, the characterization shows that of all possible compact continua from -1 to 1 (within the complex plane), the energy (minimized over $n$ points for a given compact continua) is maximized over all compact continua when the $n$ points are the zeros of the Jacobi polynomial.

More recently, regarding the first question above, Ismail and Wang developed an electrostatic interpretation of quasi-orthogonal polynomials in [7]. The main result is analogous to one given in [8]. In brief, it says that the equilibrium position of $n$ unit charges in the presence of a given external field is uniquely attained at the zeros of the associated quasi-orthogonal polynomials.

## 4. Implementation

The above method was implemented using an amalgamation of symbolic and numerical approaches in Maple 2018. As an illustration, we present the steps taken to calculate the zeros of the Laguerre polynomial $L_{9}^{(0)}(x)$.

Step 1. We implement the initial guess procedure using the asymptotic formula in the Digital Library of Mathematical Functions section 18.16. [20]. The input for the initial guess procedure is $\alpha$ and $n$ corresponding to the desired Laguerre polynomial $L_{n}^{(\alpha)}(x)$.

Step 2. We define the nonlinear system Expression 6, corresponding to the Laguerre polynomials.
Step 3. We calculate the Jacobian matrix using the built-in Maple function "Jacobian".
Step 4. For instructive purposes, we perform one iteration of Newton's method before writing a loop to iterate it ten times. We evaluate $L_{9}^{(0)}(x)$ at the approximated zeros as a quick check for accuracy. Maple produces the zeros after each iteration.

## 5. Illustrative Examples

In the following Tables 1-7, zeros approximations are listed for a variety of classical orthogonal polynomials of a specified degree $n$. The Jacobi column corresponds to the general Jacobi polynomial with $\alpha=\frac{1}{4}$ and $\beta=\frac{1}{8}$. The Chebyshev column refers to the Chebyshev polynomials of the 1 st kind, which correspond to Jacobi polynomials with $\alpha=\beta=\frac{-1}{2}$. The Gegenbauer column corresponds to Jacobi polynomials with $\alpha=\beta=\frac{1}{4}$. The Legendre column corresponds to Jacobi polynomials with $\alpha=\beta=0$. The Laguerre column corresponds to the classical Laguerre polynomials. The General Laguerre column corresponds to Laguerre polynomials with $\alpha=1$.

These results are obtained by using a straightforward implementation of Newton's method in the following way: Let $n$ be a fixed natural number and consider the vector $\vec{x}=\left(x_{1}, x_{2}, \cdots, x_{n}\right)$ which contains the zeros of the orthogonal polynomial of degree $n$ and $\vec{f}=\left(f_{1}, f_{2}, \cdots, f_{n}\right)$ be a vectorvalued function. With this notation, we can write the system of equations as $\vec{f}(\vec{x})=\overrightarrow{0}$. The nonlinear equation above is represented by Expression 4 in the case of the Jacobi polynomials, by Expression 5 in the case of the generalized Laguerre polynomials and by Expression 6 in the case of the Hermite polynomials. As for the initial guess, we relied on formulas given in Section 18.16 of [20].

Since the exact roots are known for the Chebyshev case, one may calculate the exact error. Thus, the same can be said for Vieté-Pell and Vieté-Pell-Lucas polynomials. Using the infinity norm we have for $n=20$ the exact error is $6.749 \times 10^{-17}$, while for $n=25$ the exact error is $6.297 \times 10^{-17}$. We provide error estimates in each case using the infinity norm.

Table 1. Error estimates for $n=20$

| Polynomial | Error Estimate |
| :--- | :---: |
| Legendre | $1.6064700823479085388 \times 10^{-16}$ |
| General Jacobi $\alpha=1 / 4, \beta=1 / 8$ | $2.0443258006786251481 \times 10^{-16}$ |
| Gegenbauer | $2.4276213934271014550 \times 10^{-16}$ |
| Chebyshev 1st Kind | $2.775557561562891350 \times 10^{-17}$ |
| Classical Laguerre | $7.0122389569333584353 \times 10^{-15}$ |
| General Laguerre $\alpha=1$ | $1.0850726264919494635 \times 10^{-14}$ |
| Hermite | $1.2572574676652352260 \times 10^{-16}$ |

Table 2. Error estimates for $n=25$

| Polynomial | Error Estimate |
| :--- | :---: |
| Legendre | $2.1554887097997079110 \times 10^{-16}$ |
| General Jacobi $\alpha=1 / 4, \beta=1 / 8$ | $1.1129640277756032144 \times 10^{-16}$ |
| Gegenbauer | $1.4290762156055028002 \times 10^{-16}$ |
| Chebyshev 1st Kind | $1.3834655062070259971 \times 10^{-16}$ |
| Classical Laguerre | $8.9260826473499668326 \times 10^{-15}$ |
| General Laguerre $\alpha=1$ | $2.4825341532472729961 \times 10^{-16}$ |
| Hermite | $4.7043788112778503159 \times 10^{-16}$ |

Table 3. Newton's Method results for $n=20$ and 30 iterations

| Jacobi | Chebyshev | Gegenbauer |
| :--- | :--- | :--- |
| -0.992143445584654 | -0.996917333733128 | -0.991034230192877 |
| -0.962098494639669 | -0.972369920397677 | -0.959770495283156 |
| -0.90991914333223 | -0.923879532511287 | -0.906555627647643 |
| -0.83679724371729 | -0.852640164354092 | -0.832601034386276 |
| -0.744414638606914 | -0.760405965600031 | -0.739597864903566 |
| -0.634897399553407 | -0.649448048330184 | -0.629673706991205 |
| -0.510766182525352 | -0.522498564715949 | -0.505343420884813 |
| -0.374878073128636 | -0.382683432365090 | -0.369451505240359 |
| -0.230360787671044 | -0.233445363855905 | -0.22510699141448 |
| -0.080540669675107 | -0.0784590957278449 | -0.0756123031135758 |
| 0.071133877871622 | 0.078459095727845 | 0.0756123031135758 |
| 0.221171767113119 | 0.233445363855905 | 0.22510699141448 |
| 0.366119581638305 | 0.382683432365090 | 0.369451505240359 |
| 0.502641066039214 | 0.522498564715949 | 0.505343420884813 |
| 0.627593920566186 | 0.649448048330184 | 0.629673706991205 |
| 0.738102136937797 | 0.760405965600031 | 0.739597864903566 |
| 0.831622222573934 | 0.852640164354092 | 0.832601034386276 |
| 0.906001841773546 | 0.923879532511287 | 0.906555627647643 |
| 0.959529848266796 | 0.972369920397677 | 0.959770495283156 |
| 0.99098031100982 | 0.996917333733128 | 0.991034230192877 |

Table 4. Newton's Method results for $n=20$ and 30 iterations

| Legendre | Laguerre | General Laguerre |
| :--- | :--- | :--- |
| -0.993128599185095 | 0.0705398896919887 | 0.174906752386615 |
| -0.963971927277914 | 0.372126818001611 | 0.587303080638269 |
| -0.912234428251326 | 0.916582102483273 | 1.23822510183424 |
| -0.839116971822219 | 1.70730653102834 | 2.13139626007693 |
| -0.746331906460151 | 2.74919925530943 | 3.27213313351699 |
| -0.636053680726515 | 4.04892531385089 | 4.66749446588836 |
| -0.510867001950827 | 5.61517497086162 | 6.32653619767384 |
| -0.37370608871542 | 7.45901745367106 | 8.26067095201373 |
| -0.227785851141645 | 9.5943928695811 | 10.4841673812082 |
| -0.0765265211334974 | 12.0388025469643 | 13.0148487721526 |
| 0.0765265211334973 | 14.8142934426307 | 15.8750870127848 |
| 0.227785851141645 | 17.9488955205194 | 19.0932519076063 |
| 0.373706088715419 | 21.478788240285 | 22.7058938881731 |
| 0.510867001950827 | 25.4517027931869 | 26.7611702293794 |
| 0.636053680726515 | 29.9325546317006 | 31.3245161370075 |
| 0.746331906460151 | 35.013434240479 | 36.4887033461491 |
| 0.839116971822219 | 40.8330570567286 | 42.3934227457745 |
| 0.912234428251326 | 47.6199940473465 | 49.2688138498685 |
| 0.963971927277914 | 55.8107957500639 | 57.5544209713148 |
| 0.993128599185095 | 66.5244165256157 | 68.3770378145523 |

Table 5. Newton's Method results for $n=25$ and 30 iterations

| Jacobi | Chebyshev | Gegenbauer |
| :--- | :--- | :--- |
| -0.994901665878463 | -0.998026728428272 | -0.994174685362604 |
| -0.975360959985654 | -0.982287250728689 | -0.973813483540093 |
| -0.941256322689963 | -0.951056516295154 | -0.938979875687483 |
| -0.893091307988287 | -0.90482705246602 | -0.890187770804335 |
| -0.831584665110590 | -0.844327925502015 | -0.828161987824607 |
| -0.757655035013272 | -0.770513242775789 | -0.75382448992158 |
| -0.672406769138576 | -0.684547105928689 | -0.668280361715944 |
| -0.577113343604359 | -0.587785252292473 | -0.57280131807384 |
| -0.473198311079934 | -0.481753674101715 | -0.468806780981076 |
| -0.362214026547642 | -0.368124552684678 | -0.357842771895352 |
| -0.245818453819013 | -0.248689887164855 | -0.241558925568652 |
| -0.125750396162197 | -0.125333233564304 | -0.121683964806954 |
| -0.0038035200079399 | $8.36062906219094 \mathrm{E}-18$ | $2.87922513006768 \mathrm{E}-17$ |
| 0.118200440621912 | 0.125333233564304 | 0.121683964806954 |
| 0.238438898854630 | 0.248689887164855 | 0.241558925568652 |
| 0.355115642426439 | 0.368124552684678 | 0.357842771895352 |
| 0.466487667212620 | 0.481753674101715 | 0.468806780981076 |
| 0.570891216112889 | 0.587785252292473 | 0.57280131807384 |
| 0.666766634609609 | 0.684547105928689 | 0.668280361715944 |
| 0.752681672462637 | 0.770513242775789 | 0.75382448992158 |
| 0.827352885709386 | 0.844327925502015 | 0.828161987824607 |
| 0.889664827092574 | 0.904827052466020 | 0.890187770804335 |
| 0.938686772318027 | 0.951056516295154 | 0.938979875687483 |
| 0.973686941970036 | 0.982287250728689 | 0.973813483540093 |
| 0.994146438181037 | 0.998026728428272 | 0.994174685362604 |
|  |  |  |

Table 6. Newton's Method results for $n=25$ and 30 iterations

| Legendre | Laguerre | General Laguerre |
| :--- | :--- | :--- |
| -0.995556969790498 | 0.0567047754527055 | 0.141236726258096 |
| -0.976663921459518 | 0.299010898586989 | 0.473974537884425 |
| -0.942974571228974 | 0.735909555435016 | 0.998383405621479 |
| -0.894991997878275 | 1.36918311603519 | 1.71638168719236 |
| -0.833442628760834 | 2.20132605372147 | 2.63069311458477 |
| -0.759259263037358 | 3.23567580355804 | 3.7448777262027 |
| -0.673566368473468 | 4.47649661507383 | 5.06340831233858 |
| -0.577662930241223 | 5.92908376270045 | 6.59177560687321 |
| -0.473002731445715 | 7.59989930995675 | 8.33662635980513 |
| -0.361172305809388 | 9.49674922093243 | 10.3059430256137 |
| -0.243866883720988 | 11.6290149117788 | 12.5092780113164 |
| -0.12286469261071 | 14.0079579765451 | 14.9580612826525 |
| $-3.94351965660777 \mathrm{E}-18$ | 16.6471255972888 | 17.6660089928416 |
| 0.12286469261071 | 19.5628980114691 | 20.6496747456588 |
| 0.243866883720988 | 22.775241986835 | 23.9292078044927 |
| 0.361172305809388 | 26.3087723909689 | 27.5294209021358 |
| 0.473002731445715 | 30.1942911633161 | 31.481337894211 |
| 0.577662930241223 | 34.471097571922 | 35.8245167628475 |
| 0.673566368473468 | 39.1906088039374 | 40.61069001566 |
| 0.759259263037358 | 44.422349336162 | 45.9097868582297 |
| 0.833442628760834 | 50.2645749938335 | 51.8206158754045 |
| 0.894991997878275 | 56.8649671739402 | 58.4916748142772 |
| 0.942974571228974 | 64.4666706159541 | 66.1674493598106 |
| 0.976663921459518 | 73.5342347921002 | 75.315081358106 |
| 05969790498 | 85.260155562496 | 87.1338948199813 |

Table 7. Newton's Method results for $n=12$ and 30 iterations

| Hermite |
| :--- |
| 0.440147298645308 |
| 0.881982756213821 |
| 1.32728070207308 |
| 1.77800112433715 |
| 2.23642013026728 |
| 2.70532023717303 |
| 3.1882949244251 |
| 3.69028287699836 |
| 4.21860944438656 |
| 4.78532036735222 |
| 5.41363635528003 |
| 6.16427243405245 |

## 6. Conclusion

We have presented a unified approach for calculating the zeros of the classical orthogonal polynomials and provided examples involving the Jacobi polynomials, including Chebyshev and Gengebauer, the General Laguerre polynomials, including Legendre and Laguerre and the Hermite polynomials. We are working on a similar approach that works for more general classes of polynomials, the Heine-Stieltjes polynomials. The difficulty lies in choosing a decent guess for the zeros of the given Heine-Stieltjes polynomial. We have had some success using the electrostatic interpretation for the initial guess, but more work is needed. Other future studies include expanding the family of orthogonal polynomials to which this method applies, expanding the electrostatic interpretation to other families of polynomials, such as the generalized Bessel polynomials, and exploring connections between orthogonal polynomials and Lucas polynomial identities, such as was done in [21].

## Author Contributions

All the authors equally contributed to this work. They all read and approved the final version of the paper.

## Conflicts of Interest

All the authors declare no conflict of interest.

## References

[1] A. M. Legendre, Recherches sur L’attraction des Sphéroïdes Homogènes, Universitätsbibliothek Johann Christian Senckenberg 1785 (1785) 411-434.
[2] G. Szegö, Orthogonal Polynomials, 4th Edition, American Mathematical Society, Rhode Island, 1975.
[3] A. Alhaidari, Representation of the Quantum Mechanical Wavefunction by Orthogonal Polynomials in the Energy and Physical Parameters, Communications in Theoretical Physics 72 (1) (2019) 01510415 pages.
[4] T. M. Dunster, A. Gil, D. Ruiz-Antolín, J. Segura, Computation of the Reverse Generalized Bessel Polynomials and Their Zeros, Computational and Mathematical Methods 3 (6) (2021) e1198 12 pages.
[5] B. Kuloğlu, E. Özkan, A. G. Shannon, Incomplete Generalized Vieta-Pell and Vieta-Pell-Lucas Polynomials, Notes on Number Theory and Discrete Mathematics 27 (4) (2021) 245-256.
[6] D. Tasci, F. Yalcin, Vieta-Pell and Vieta-Pell-Lucas Polynomials, Advances in Difference Equations 2013 (2013) Article Number 2248 pages.
[7] M. E. H. Ismail, X.-S. Wang, On Quasi-Orthogonal Polynomials: Their Differential Equations, Discriminants and Electrostatics, Journal of Mathematical Analysis and Applications 474 (2) (2019) 1178-1197.
[8] M. E. H. Ismail, An Electrostatics Model for Zeros of General Orthogonal Polynomials, Pacific Journal of Mathematics 193 (2) (2000) 355-369.
[9] M. E. H. Ismail, More on Electrostatic Models for Zeros of Orthagonal Polynomials, Numerical Functional Analysis and Optimization 21 (1) (2007) 191-204.
[10] A. N. Lowan, N. Davids, A. Levenson., Table of the Zeros of the Legendre Polynomials of Order 1-16 and the Weight Coefficients for Gauss' Mechanical Quadrature Formula, Bulletin of the American Mathematical Society 48 (10) (1942) 739-743.
[11] R. E. Greenwood, J. J. Miller, Zeros of the Hermite Polynomials and Weights for Gauss' Mechanical Quadrature Formula, Bulletin of the American Mathematical Society 54 (1948) 765-769.
[12] H. E. Salzer, R. Zucker, Table of the Zeros and Weight Factors of the First Fifteen Laguerre Polynomials, Bulletin of the American Mathematical Society 55 (10) (1949) 1004-1012.
[13] H. L. Krall, O. Frink, A New Class of Orthogonal Polynomials: The Bessel Polynomials, Transactions of the American Mathematical Society 65 (1) (1949) 100-115.
[14] L. Pasquini, Polynomial Solutions to Second Order Linear Homogeneous Ordinary Differential Equations. Properties and Approximation, Calcolo 26 (1989) 167-183.
[15] L. Pasquini, On the Computation of the Zeros of the Bessel Polynomials, in: R. V. M. Zahar (Ed.), Approximation and Computation: A Festschrift in Honor of Walter Gautschi, Vol. 119 of ISNM International Series of Numerical Mathematics, Birkhäuser, Boston, 1994, pp. 511-534.
[16] L. Pasquini, Accurate Computation of the Zeros of the Generalized Bessel Polynomials, Numerische Mathematik 86 (3) (2000) 507-538.
[17] S. Steinerberger, Electrostatic Interpretation of Zeros of Orthogonal Polynomials, Proceedings of the American Mathematical Society 146 (12) (2018) 5323-5331.
[18] J. E. Marsden, M. J. Hoffman, Elementary Classical Analysis, 2nd Edition, W. H. Freeman, San Francisco, 1993.
[19] F. Marcellán, A. Martínez-Finkelshtein, P. Martínez-González, Electrostatic Models for Zeros of Polynomials: Old, New, and Some Open Problems, Journal of Computational and Applied Mathematics 207 (2) (2007) 258-272.
[20] F. W. J. Olver, A. B. Olde Daalhuis, D. W. Lozier, B. I. Schneider, R. F. Boisvert, C. W. Clark, B. R. Miller, B. V. Saunders, H. S. Cohl, M. A. McClain, NIST Digital Library of Mathematical Functions (2010), http://dlmf.nist.gov/, Accessed 20 Nov 2023 to Release 1.1.0 of 2020-12-15.
[21] W. M. Abd-Elhameed, A. Napoli, Some Novel Formulas of Lucas Polynomials via Different Approaches, Symmetry 15 (1) (2023) 18519 pages.


[^0]:    $\overline{{ }^{1} \text { rmoussa@nsu.edu; }{ }^{2} \text { jetipton@nsu.edu (Corresponding Author) }}$
    ${ }^{1,2}$ Department of Mathematics, College of Science, Engineering, and Technology, Norfolk State University, Norfolk, United States

